

STABILITY AND INSTABILITY OF
PERIODIC SOLUTIONS OF A DAMPED WAVE
EQUATION IN A THIN DOMAIN

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1. Introduction

In the previous papers [5] and [6] the authors showed the existence of periodic solutions

$$w^\varepsilon = \begin{pmatrix} u^\varepsilon \\ v^\varepsilon \end{pmatrix}$$

with respect to the time t of a damped wave system in the non-autonomous and autonomous cases respectively.

The considered system in the non-autonomous case is of the form

$$(1) \quad \begin{cases} \frac{\partial u}{\partial t} = v \\ \frac{\partial v}{\partial t} = \Delta_X u + \frac{\partial^2 u}{\partial Y^2} - \beta v - \alpha u + g(t, X, Y, u) \end{cases}$$

with Neumann boundary condition:

$$(2) \quad \frac{\partial u}{\partial \nu_\varepsilon} = 0 \quad \text{on } \partial Q_\varepsilon,$$

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where α and β are positive constants, g is an appropriate smooth function T -periodic with respect to time t , and (X, Y) is a generic point of the "thin domain" $Q_\varepsilon = \Omega \times (0, \varepsilon) \subset \mathbb{R}^{N+1}$.

The method employed in [5] and [6] consists in assuming that the "reduced" problem at $\varepsilon = 0$ in the domain Ω admits an isolated T_0 -periodic solution

$$w^0 = \begin{pmatrix} u^0 \\ v^0 \end{pmatrix},$$

$T_0 = T$ in the non-autonomous case, and then in searching for conditions under which this solution extends to one for the problem (1)-(2) in Q_ε . The main tool is the topological degree for nonlinear compact operators.

It must be observed that in the autonomous case, i.e. when g is independent of t in (1), the assumed T_0 -periodic solution of the reduced problem is not isolated. To overcome this difficulty we normalize the unknown period $T > 0$, in general different from T_0 , of the sought-after periodic solution of (1)-(2) by introducing T as a parameter in system (1) by means of the substitution $t \rightarrow (T_0/T)t$.

Furthermore, in this case additional assumptions are required on the linearized reduced system. Under these assumptions it is possible to prove the existence of a continuous functional $T = T(w)$, $w = \begin{pmatrix} u \\ v \end{pmatrix}$, such that $T(w^0) = T_0$ and such that w^0 is an isolated fixed point with topological index different from zero of the $T(\cdot)$ -parametrized reduced problem.

The aim of this paper is to derive the stability properties of the periodic solution w^ε defined in Q_ε , for small $\varepsilon > 0$, from those of the T_0 -periodic solution w^0 in Ω .

Specifically in the non-autonomous case, we will prove that if the latter is stable or unstable then for $\varepsilon > 0$ sufficiently small the former is also stable or unstable. This result will be obtained by considering the first order approximation L^ε of the Poincaré map V^ε associated to (1)-(2) at w^ε . It is well known (see for instance [2] and [3]) that if all the $\lambda \in \sigma(L^\varepsilon)$, the spectrum of L^ε , satisfy the inequality $|\lambda| \leq q < 1$ then w^ε is stable. On the contrary, if there exists $\lambda \in \sigma(L^\varepsilon)$ such that $|\lambda| > 1$ then w^ε is unstable. In our case these situations can be treated by using the fact that L^ε is a condensing operator with constant $k < 1$ (see [7] and [8]) and the properties of its spectrum. In fact, it turns out (see [1]) that if $\lambda \in \sigma(L^\varepsilon)$ satisfies $|\lambda| > k + d$, whenever $d > 0$, then it is an eigenvalue of finite multiplicity.

The same will be done for the autonomous case to obtain orbital (in)stability of the T -periodic solution w^ε defined in Q_ε from that of the T_0 -periodic solution w^0 defined in Ω . The additional problem in this case is that we must prove the simplicity of the eigenvalue 1 of the linearization of (1) around w^ε for $\varepsilon > 0$

sufficiently small, from that at $\varepsilon = 0$. Obviously, the assumptions for orbital (in)stability will concern all the other eigenvalues of the spectrum of the linearization.

The paper is organized as follows. In Section 2 we provide assumptions, definitions and preliminary results to be used in the sequel. In Section 3 we treat the non-autonomous case and in Section 4 the autonomous one.

2. Assumptions, definitions and preliminary results

We first consider the case when g depends on t and we assume the following conditions on $g : [0, T] \times \Omega \times [0, \varepsilon_0) \times \mathbb{R} \rightarrow \mathbb{R}$:

- g is of class C^1 jointly in the variables t, X, Y and u and it is T -periodic in $t : g(t + T, X, Y, u) \equiv g(t, X, Y, u)$. Moreover, g satisfies the following estimates:

$$\begin{aligned} |g_X(t, X, Y, u)| &\leq a(1 + |u|^{\theta+1}), \\ |g_Y(t, X, Y, u)| &\leq a(1 + |u|^{\theta+1}), \\ |g_u(t, X, Y, u)| &\leq a(1 + |u|^\theta), \end{aligned}$$

for all values of its arguments t, X, Y, u . Here $a > 0$ is a suitable constant and $\theta \in [0, \infty)$ if $N = 1$, $\theta \in [0, 2/(N - 1))$ if $N > 1$.

Observe that the growth rate θ is strictly less than the critical value $2/(N - 1)$. This is because the validity of the Sobolev compact embedding result is crucial in our approach.

Following [4], for fixed $\varepsilon > 0$ we introduce new variables $X = x, Y = \varepsilon y$. System (1) becomes

$$(3) \quad \begin{cases} \frac{\partial u}{\partial t} = v, \\ \frac{\partial v}{\partial t} = \Delta_x u + \frac{1}{\varepsilon^2} \frac{\partial^2 u}{\partial y^2} - \beta v - \alpha u + g(t, x, \varepsilon y, u) \end{cases}$$

and boundary condition (2) takes the form

$$\frac{\partial u}{\partial \nu} = 0 \quad \text{on } \partial Q,$$

where $Q = \Omega \times (0, 1)$ and ν denotes the outward unit normal vector to Q . We suppose that Ω is a C^2 -smooth domain.

For the reader convenience, we now give the most relevant definitions which permit to rewrite (1)-(2) as a fixed point problem in a suitable space. More details can be found in [5].

Following [5] (which in turn follows Hale-Raugel [4]), we introduce the following Banach spaces when $\varepsilon > 0$. Let X_ε^1 be the space $H^1(Q)$ with the norm

$$\left(\|u\|_{1Q}^2 + \frac{1}{\varepsilon^2} \left\| \frac{\partial u}{\partial y} \right\|_{0Q}^2 \right)^{1/2}.$$

Here and below, $\|\cdot\|_{0Q}$ denotes the norm in $L^2(Q)$ and $\|\cdot\|_{1Q}$ that in $H^1(Q)$. Let $U_\varepsilon(t)$ be the semigroup generated by the system of linear equations

$$\begin{cases} \frac{\partial u}{\partial t} = v, \\ \frac{\partial v}{\partial t} = \Delta_x u + \frac{1}{\varepsilon^2} \frac{\partial^2 u}{\partial y^2} - \beta v - \alpha u, \end{cases}$$

with boundary condition (2). It is known (see [5]) that $U_\varepsilon(t)$ is a C_0 -semigroup in the space

$$Y_\varepsilon^1 = X_\varepsilon^1 \times L^2(Q) \ni (u, v) = w.$$

One has the exponential estimate

$$\|U_\varepsilon(t)\|_{Y_\varepsilon^1 \rightarrow Y_\varepsilon^1} \leq ce^{-\gamma t}, \quad (t \geq 0),$$

where $c, \gamma > 0$. By introducing for $\varepsilon > 0$ the linear operator

$$A_\varepsilon = \begin{pmatrix} 0 & I \\ \Delta_x + \frac{1}{\varepsilon^2} \frac{\partial^2}{\partial y^2} - \alpha & -\beta \end{pmatrix}$$

with Neumann boundary condition, we can write

$$U_\varepsilon(t) = e^{A_\varepsilon t}, \quad t \geq 0.$$

In the sequel by a solution of any differential equation we mean a solution of the corresponding integral equation obtained by the variation-of-constants formula.

Now let $C_T(Y_\varepsilon^1)$ be the space of all continuous, T -periodic functions $w = \begin{pmatrix} u \\ v \end{pmatrix}$ from \mathbb{R} into Y_ε^1 with the usual norm

$$\|w\| = \sup_{t \in [0, T]} \|w(t)\|_{Y_\varepsilon^1}.$$

Define the following maps on $C_T(Y_\varepsilon^1)$:

$$f_\varepsilon(w)(t)(x, y) = \begin{pmatrix} 0 \\ g(t, x, \varepsilon y, u(t, x, y)) \end{pmatrix}$$

and

$$J_\varepsilon w(t) = U_\varepsilon(t)(I - U_\varepsilon(T))^{-1} \int_0^T U_\varepsilon(T-s)w(s) ds + \int_0^t U_\varepsilon(t-s)w(s) ds.$$

Then define

$$F_\varepsilon(w) = J_\varepsilon f_\varepsilon(w).$$

Using the Sobolev embedding theorem together with the theory of nonlinear Nemytskii operators, it is easy to show that F_ε maps $C_T(Y_\varepsilon^1)$ into itself and is completely continuous, i.e. it is continuous and it maps bounded sets into relatively compact sets. We give now the following

Definition 1. A fixed point of the completely continuous operator $F_\varepsilon : C_T(Y_\varepsilon^1) \rightarrow C_T(Y_\varepsilon^1)$ is a T -periodic solution of (1)-(2).

It is known that a fixed point of F_ε is always a T -periodic distributional solution of (1)-(2).

Next we pose the limit problem at $\varepsilon = 0$. Let $U_0(t)$ ($t \geq 0$) be the semigroup generated by the linear system

$$\begin{cases} \frac{\partial u}{\partial t} = v, \\ \frac{\partial v}{\partial t} = \Delta_x u - \beta v - \alpha u, \end{cases}$$

with the Neumann boundary condition

$$\frac{\partial u}{\partial \nu} = 0 \quad \text{on } \partial\Omega.$$

Observe that $U_0(t) = e^{A_0 t}$, $t \geq 0$, where

$$A_0 = \begin{pmatrix} 0 & I \\ \Delta_x - \alpha & -\beta \end{pmatrix}$$

with Neumann boundary condition.

Let $w_0 = \begin{pmatrix} u_0 \\ v_0 \end{pmatrix}$ be an element of $H^1(\Omega) \times L^2(\Omega)$. Then $U_0(t) \begin{pmatrix} u_0 \\ v_0 \end{pmatrix}$ is in $H^1(\Omega) \times L^2(\Omega)$ and one has the estimate

$$\|U_0(t)\|_{H^1(\Omega) \times L^2(\Omega) \rightarrow H^1(\Omega) \times L^2(\Omega)} \leq ce^{-\gamma t},$$

where $c, \gamma > 0$. Defining $i : \Omega \rightarrow Q$ by $i(x) = (x, 0)$, we obtain an inclusion $\mathcal{J} : H^1(\Omega) \times L^2(\Omega) \rightarrow Y_\varepsilon^1$ with $\mathcal{J}(u, v)(x, y) = (u(x), v(x))$. The map \mathcal{J} is an isometry for all $0 < \varepsilon < \varepsilon_0$, and we identify $U_0(t) \begin{pmatrix} u_0 \\ v_0 \end{pmatrix}$ with the element $\mathcal{J}U_0(t) \begin{pmatrix} u_0 \\ v_0 \end{pmatrix}$ of Y_ε^1 .

Define an operator F_0 on $C_T(H^1(\Omega) \times L^2(\Omega))$ as follows:

$$F_0(w) = J_0 f_0(w),$$

where J_0 has the same form as J_ε with $U_\varepsilon(t)$ replaced by $U_0(t)$ and

$$f_0(w)(t)(x) = \begin{pmatrix} 0 \\ g(t, x, 0, u(t, x)) \end{pmatrix}.$$

Then $F_0 : C_T(H^1(\Omega) \times L^2(\Omega)) \rightarrow C_T(H^1(\Omega) \times L^2(\Omega))$ and it is completely continuous.

We identify the T -periodic solutions of the system

$$(4) \quad \begin{cases} \frac{\partial u}{\partial t} = v, \\ \frac{\partial v}{\partial t} = \Delta_x u - \beta v - \alpha u + g(t, x, 0, u) \end{cases}$$

together with the Neumann boundary condition

$$(5) \quad \frac{\partial u}{\partial \nu} = 0 \quad \text{on } \partial\Omega$$

with the fixed points of the operator F_0 . The main result proved in [5] is the following existence result, here $\text{ind}(\cdot, \cdot)$ indicates the topological index.

Theorem A. *If the problem (4)-(5) admits an isolated T -periodic solution $w^0 = \begin{pmatrix} u^0 \\ v^0 \end{pmatrix} \in C_T(H^1(\Omega) \times L^2(\Omega))$ with $\text{ind}(F_0, w^0) \neq 0$, then for sufficiently small $\varepsilon > 0$ the problem (4)-(5) admits a T -periodic solution $w^\varepsilon = \begin{pmatrix} u^\varepsilon \\ v^\varepsilon \end{pmatrix} \in C_T(Y_\varepsilon^1)$ and*

$$\|w^\varepsilon - \mathcal{J}w^0\|_{C_T(Y_\varepsilon^1)} \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

The proof of Theorem A is mainly based on the following result, which we repeat here for the reader's convenience since it will be used in the next sections.

Lemma A. *Suppose that there exist $r > 0$, $\varepsilon_n \rightarrow 0$ and*

$$\begin{pmatrix} u^* \\ v^* \end{pmatrix} \in C_T(H^1(\Omega) \times L^2(\Omega))$$

such that the problem (1), (2) admits T -periodic solutions

$$\begin{pmatrix} u_n \\ v_n \end{pmatrix} \in C_T(Y_{\varepsilon_n}^1)$$

with $\left\| \begin{pmatrix} u_n \\ v_n \end{pmatrix} - \mathcal{J} \begin{pmatrix} u^ \\ v^* \end{pmatrix} \right\|_{C_T(Y_{\varepsilon_n}^1)} = r$. Then there exist a T -periodic solution*

$\begin{pmatrix} \bar{u} \\ \bar{v} \end{pmatrix}$ of (4)-(5) and a subsequence $\left\{ \begin{pmatrix} u_{k_n} \\ v_{k_n} \end{pmatrix} \right\}$ of $\left\{ \begin{pmatrix} u_n \\ v_n \end{pmatrix} \right\}$ such that

$$\left\| \begin{pmatrix} u_{k_n} \\ v_{k_n} \end{pmatrix} - \mathcal{J} \begin{pmatrix} \bar{u} \\ \bar{v} \end{pmatrix} \right\|_{C_T(Y_{\varepsilon_n}^1)} \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

with

$$\left\| \begin{pmatrix} \bar{u} \\ \bar{v} \end{pmatrix} - \begin{pmatrix} u^* \\ v^* \end{pmatrix} \right\|_{C_T(H^1(\Omega) \times L^2(\Omega))} = r.$$

Finally, for the autonomous case

$$(6) \quad \begin{cases} \frac{\partial u}{\partial t} = v, \\ \frac{\partial v}{\partial t} = \Delta_x u + \frac{1}{\varepsilon^2} \frac{\partial^2 u}{\partial y^2} - \beta v - \alpha u + g(x, \varepsilon y, u) \end{cases}$$

together with Neumann boundary conditions

$$(7) \quad \frac{\partial u}{\partial \nu} = 0 \quad \text{on } \partial Q,$$

the substitution $t \rightarrow (T_0/T)t$ produces the dependence on T of all the operators introduced before. Specifically, as it can be easily verified we have

$$F_\varepsilon(T, w) = J_\varepsilon(T) f_\varepsilon(T, w),$$

where

$$f_\varepsilon(T, w)(t)(x, y) = \begin{pmatrix} 0 \\ (T/T_0)g(x, \varepsilon y, u(t, x, y)) \end{pmatrix},$$

$$J_\varepsilon(T)w(t) = U_\varepsilon(T, t)[I - U_\varepsilon(T, T_0)]^{-1} \int_0^T U_\varepsilon(T, T_0 - s)w(s) ds$$

$$+ \int_0^t U_\varepsilon(T, t - s)w(s) ds,$$

and $U_\varepsilon(T, t)$ is the semigroup generated by

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{T}{T_0}v, \\ \frac{\partial v}{\partial t} = \frac{T}{T_0} \left[\Delta_x u + \frac{1}{\varepsilon^2} \frac{\partial^2 u}{\partial y^2} - \beta v - \alpha u \right]. \end{cases}$$

Similar formulas hold for $\varepsilon = 0$. Obviously, a fixed point of $F_\varepsilon(T, \cdot) : C_{T_0}(Y_\varepsilon^1) \rightarrow C_{T_0}(Y_\varepsilon^1)$ for some $T > 0$ is a T -periodic solution of (6)-(7).

The following existence result was proved in [6].

Theorem B. *Suppose that the system*

$$\begin{cases} \frac{\partial u}{\partial t} = v, \\ \frac{\partial v}{\partial t} = \Delta_x u - \beta v - \alpha u - g(x, 0, u) \end{cases}$$

together with

$$\frac{\partial u}{\partial \nu} = 0 \quad \text{on } \partial \Omega$$

has a T_0 -periodic solution $w^0 = \begin{pmatrix} u^0 \\ v^0 \end{pmatrix}$ in the classical sense such that the linearized system

$$\begin{aligned} \frac{\partial \varphi}{\partial t} &= \psi, \\ \frac{\partial \psi}{\partial t} &= \Delta_x \varphi - \beta \psi - \alpha \varphi + g_u(x, 0, u^0(t, x)) \varphi \end{aligned}$$

has no T_0 -periodic solutions which are linearly independent of $(\partial w^0 / \partial t)$. Furthermore, we suppose that it does not possess any solution of the form $\tilde{w}(t, x) + (t/T_0)w^0(t, x)$, where $\tilde{w} = \begin{pmatrix} \tilde{\varphi} \\ \tilde{\psi} \end{pmatrix}$ is T_0 -periodic with respect to t . Then for sufficiently small $\varepsilon > 0$ problem (6)-(7) admits a T_ε -periodic solution $w^\varepsilon = \begin{pmatrix} u^\varepsilon \\ v^\varepsilon \end{pmatrix}$ with $T_\varepsilon \rightarrow T_0$ and

$$\|\hat{w}^\varepsilon - \mathcal{J}w^0\|_{C_{T_0}(Y_\varepsilon^1)} \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0,$$

where $\hat{w}^\varepsilon(t) = w^\varepsilon((T_\varepsilon/T_0)t)$.

In the next two sections, for $\varepsilon > 0$ sufficiently small, we investigate the stability of the periodic solution w^ε of (1)-(2) (resp. (6)-(7)).

3. The non-autonomous case

For $\varepsilon > 0$ define the Poincaré map $V^\varepsilon : Y_\varepsilon^1 \rightarrow Y_\varepsilon^1$ associated to (1)-(2) as follows:

$$V^\varepsilon(p) = U_\varepsilon(T)p + \int_0^T U_\varepsilon(T-s)f_\varepsilon(w)(s) ds,$$

where $w(t) \in Y_\varepsilon^1$, $t \in [0, T]$, is a solution of (1)-(2) with $w(0) = p$ and T is the fixed period of the nonlinearity g .

As a direct consequence of Theorem A we have that for $\varepsilon > 0$ sufficiently small the Poincaré map has a fixed point $w^\varepsilon(0) \in Y_\varepsilon^1$ which represents the initial conditions of the T -periodic solution w^ε of (1)-(2).

Consider the linearization $L^\varepsilon : Y_\varepsilon^1 \rightarrow Y_\varepsilon^1$ of V^ε around w^ε :

$$L^\varepsilon q = U_\varepsilon(T)q + \int_0^T U_\varepsilon(T-s)f'_\varepsilon(w^\varepsilon(s))\psi(s) ds,$$

where $\psi(t) \in Y_\varepsilon^1$, $t \in [0, T]$, is the solution of the linearization of (1) around w^ε such that $\psi(0) = q$.

For $\varepsilon = 0$ we also define $V^0 : H^1(\Omega) \times L^2(\Omega) \rightarrow H^1(\Omega) \times L^2(\Omega)$ and the corresponding linearization L^0 around w^0 . The linear map $L^\varepsilon : Y_\varepsilon^1 \rightarrow Y_\varepsilon^1$ is k -condensing with respect to the measure of noncompactness of Kuratovskii generated by a suitable equivalent norm in the space Y_ε^1 (see [8]). Moreover, in [7] this condensivity property was proved for some special measures of noncompactness defined by means of the Hausdorff measure of noncompactness.

It follows that (see [1]) for any $d > 0$ the points $\lambda \in \sigma(L^\varepsilon)$ for which $|\lambda| > k+d$ are eigenvalues of finite multiplicity.

In the sequel we will study the stability of w^ε by means of the properties of the spectrum of $L^0 : H^1(\Omega) \times L^1(\Omega) \rightarrow H^1(\Omega) \times L^2(\Omega)$ and the corresponding stability results [1]. In this section we assume the conditions of Theorem A.

We will first prove the following result.

Theorem 1. *Assume that for any $\lambda \in \sigma(L^0)$ we have that $|\lambda| < 1$. Then for sufficiently small $\varepsilon > 0$ the T -periodic solution w^ε of (1)-(2) is stable.*

Proof. Assume the contrary, then by [1] there exist two sequences $\varepsilon_n \rightarrow 0$ and $\lambda_n \in \sigma(L^{\varepsilon_n})$ such that $|\lambda_n| \geq 1$. For any $n \in \mathbb{N}$ let $q_n \in Y_{\varepsilon_n}^1$, $\|q_n\|_{Y_{\varepsilon_n}^1} = 1$ and $L^{\varepsilon_n} q_n = \lambda_n q_n$.

Put $e^{\mu_n T} = \lambda_n$, $n \in \mathbb{N}$, and let $\varphi_n(t) = e^{-\mu_n t} \psi_n(t)$, where $\psi_n(t)$ is the solution of the linearization of (1) around w^ε which we denote by

$$\dot{\psi} = A_{\varepsilon_n} \psi + B_{\varepsilon_n}(t)\psi$$

with $\psi_n(0) = q_n$. It turns out that φ_n is a T -periodic solution of the linear equation

$$(8) \quad \dot{\varphi} = (A_{\varepsilon_n} - \mu_n)\varphi + B_{\varepsilon_n}(t)\varphi.$$

In fact, we have $\varphi_n(T) = e^{-\mu_n T} \psi_n(T) = e^{-\mu_n T} \lambda_n q_n = q_n$. Thus $\varphi_n(T) = \varphi_n(0) = q_n$, moreover

$$\varphi_n(t) = e^{(A_{\varepsilon_n} - \mu_n)t} q_n + \int_0^t e^{(A_{\varepsilon_n} - \mu_n)(t-s)} B_{\varepsilon_n}(s)\varphi_n(s) ds,$$

and

$$\begin{aligned}
\varphi_n(t+T) &= e^{(A_{\varepsilon_n} - \mu_n)(t+T)} q_n + \int_0^T e^{(A_{\varepsilon_n} - \mu_n)(t+T-s)} B_{\varepsilon_n}(s) \varphi_n(s) ds \\
&\quad + \int_T^{t+T} e^{(A_{\varepsilon_n} - \mu_n)(t+T-s)} B_{\varepsilon_n}(s) \varphi_n(s) ds \\
&= e^{(A_{\varepsilon_n} - \mu_n)t} \left[e^{(A_{\varepsilon_n} - \mu_n)T} q_n + \int_0^T e^{(A_{\varepsilon_n} - \mu_n)(T-s)} B_{\varepsilon_n}(s) \varphi_n(s) ds \right] \\
&\quad + \int_0^t e^{(A_{\varepsilon_n} - \mu_n)(t-\xi)} B_{\varepsilon_n}(\xi) \varphi_n(\xi+T) d\xi \\
&= e^{(A_{\varepsilon_n} - \mu_n)t} q_n + \int_0^t e^{(A_{\varepsilon_n} - \mu_n)(t-\xi)} B_{\varepsilon_n}(\xi) \varphi_n(\xi+T) d\xi.
\end{aligned}$$

By the uniqueness of solutions of the Cauchy problem for the linearized equation we obtain that φ_n is a T -periodic solution of (8).

By Lemma A and Theorem A we get that $\varphi_n(t) \rightarrow \varphi_0(t)$ as $n \rightarrow \infty$, where $\varphi_0(t) \in H^1(\Omega) \times L^2(\Omega)$, $t \in [0, T]$, is a continuous T -periodic solution of

$$\dot{\varphi} = (A_0 - \mu_0)\varphi + B_0(t)\varphi,$$

the linearized system of (1) around w^0 , with $\lambda_0 = \lim_{n \rightarrow \infty} \lambda_n$, $\|\varphi_0(0)\| = 1$ and $e^{-\mu_0 T} = \lambda_0$. This contradicts the fact that $|\lambda| < 1$ for any $\lambda \in \sigma(L^0)$.

We state now the instability result. We first give the following lemma.

Lemma 1. *Let $q_0 \in H^1(\Omega) \times L^2(\Omega)$. Then*

$$(\lambda I - L^\varepsilon)^{-1} \mathcal{J} q_0 \rightarrow \mathcal{J}(\lambda I - L^0)^{-1} q_0 \quad \text{as } \varepsilon \rightarrow 0$$

uniformly with respect to $\lambda \in C$, where C is a circle such that $C \cap \sigma(L^0) = \emptyset$.

Proof. Note that as it is proved in Theorem 2 below, for sufficiently small $\varepsilon > 0$, $C \cap \sigma(L^\varepsilon) = \emptyset$ and so $(\lambda I - L^\varepsilon)^{-1}$ is well defined.

We argue by contradiction, then there exist $\delta_0 > 0$, $\varepsilon_n \rightarrow 0$ and $\lambda_n \rightarrow \lambda_0 \in C$, $\lambda_n \in C$, such that

$$(9) \quad \|(\lambda_n I - L^{\varepsilon_n})^{-1} \mathcal{J} q_0 - \mathcal{J}(\lambda_n I - L^0)^{-1} q_0\|_{Y_{\varepsilon_n}^1} \geq \delta_0.$$

Let $p_n = (\lambda_n I - L^{\varepsilon_n})^{-1} \mathcal{J} q_0$. We claim that the sequence $\{p_n\}$ is bounded, i.e. there exists $M > 0$ such that $\|p_n\|_{Y_{\varepsilon_n}^1} \leq M$ for any $n \in \mathbb{N}$.

In fact, assume $\|p_n\|_{Y_{\varepsilon_n}^1} \rightarrow \infty$ as $n \rightarrow \infty$ and recall that

$$\lambda_n p_n = L^{\varepsilon_n} p_n + \mathcal{J}q_0.$$

Let

$$\xi_n(t) = e^{A_{\varepsilon_n} t} p_n + \int_0^t e^{A_{\varepsilon_n}(t-s)} B_{\varepsilon_n}(s) \xi_n(s) ds,$$

hence $L^{\varepsilon_n} p_n = \xi_n(T)$. Put $z_n(t) = (\xi_n(t) / \|p_n\|_{Y_{\varepsilon_n}^1})$, thus

$$z_n(t) = e^{A_{\varepsilon_n} t} z_n(0) + \int_0^t e^{A_{\varepsilon_n}(t-s)} B_{\varepsilon_n}(s) z_n(s) ds$$

and

$$\lambda_n z_n(0) = z_n(T) + \frac{\mathcal{J}q_0}{\|p_n\|_{Y_{\varepsilon_n}^1}}.$$

Let $\lambda_n = e^{\mu_n T}$ and define

$$\eta_n(t) = e^{-\mu_n t} z_n(t).$$

Then

$$(10) \quad \eta_n(t) = e^{(A_{\varepsilon_n} - \mu_n)t} \eta_n(0) + \int_0^t e^{(A_{\varepsilon_n} - \mu_n)(t-s)} B_{\varepsilon_n}(s) \eta_n(s) ds$$

where

$$\eta_n(0) = \eta_n(T) + e^{-\mu_n T} \frac{\mathcal{J}q_0}{\|p_n\|_{Y_{\varepsilon_n}^1}}, \quad \|\eta_n(0)\|_{Y_{\varepsilon_n}^1} = 1.$$

Therefore, calculating $\eta_n(0)$ from the previous two relations and substituting in (10) we obtain

$$\begin{aligned} \eta_n(t) &= e^{(A_{\varepsilon_n} - \mu_n)t} (I - e^{(A_{\varepsilon_n} - \mu_n)T})^{-1} \int_0^T e^{(A_{\varepsilon_n} - \mu_n)(T-s)} B_{\varepsilon_n}(s) \eta_n(s) ds \\ &\quad + e^{(A_{\varepsilon_n} - \mu_n)t} (I - e^{(A_{\varepsilon_n} - \mu_n)t})^{-1} e^{-\mu_n T} \frac{\mathcal{J}q_0}{\|p_n\|_{Y_{\varepsilon_n}^1}} \\ &\quad + \int_0^t e^{(A_{\varepsilon_n} - \mu_n)(t-s)} B_{\varepsilon_n}(s) \eta_n(s) ds. \end{aligned}$$

Letting $n \rightarrow \infty$, since $\|p_n\|_{Y_{\varepsilon_n}^1} \rightarrow \infty$, Lemma A and Theorem A yield $\eta_n(t) \rightarrow \eta(t)$ where η is a T -periodic solution of

$$\dot{\varphi} = (A_0 - \mu_0)\varphi + B_0(t)\varphi$$

with $\mu_0 \in C$, which contradicts the fact that $C \cap \sigma(L^0) = \emptyset$.

Finally, by using the boundedness of $\{p_n\}$ and the same arguments as before we can prove that

$$\lambda_n p_n = L^{\varepsilon_n} p_n + \mathcal{J}q_0 \rightarrow \lambda_0 p_0 = L^0 p_0 + q_0, \quad \lambda_0 \in C,$$

which is a contradiction with (9).

We are now in the position to proving the following result.

Theorem 2. *Assume that there exists $\lambda_0 \in \sigma(L^0)$ such that $|\lambda_0| > 1$, then for sufficiently small $\varepsilon > 0$ the T -periodic solution w^ε of (1)-(2) is unstable.*

Proof. Since λ_0 is an eigenvalue of finite multiplicity (see [1]) there is a closed disc D centered at λ_0 which does not contain points of $\sigma(L^0)$ different from λ_0 and $\text{dist}(\partial D, 0) > 1$.

Furthermore, for $\varepsilon > 0$ sufficiently small there are no points of $\sigma(L^\varepsilon)$ lying on $C = \partial D$. In fact, assume there exist sequences $\varepsilon_n \rightarrow 0$ and $\lambda_n \in \sigma(L^{\varepsilon_n})$ with $\lambda_n \in C$. Then

$$\lambda_n q_n = L^{\varepsilon_n} q_n \quad \text{for some } q_n \in Y_{\varepsilon_n}^1$$

and passing to the limit as $n \rightarrow \infty$ by Theorem A we obtain

$$\widehat{\lambda}_0 q_0 = L^0 q_0$$

with $\widehat{\lambda}_0 \in C$, $q_0 \in H^1(\Omega) \times L^2(\Omega)$ which is a contradiction.

Therefore for $\varepsilon > 0$ sufficiently small the Riesz's projector

$$P_\varepsilon q = -\frac{1}{2\pi i} \int_C (\lambda I - L^\varepsilon)^{-1} q d\lambda$$

is well defined.

Let $q_0 \in H^1(\Omega) \times L^2(\Omega)$ such that $\lambda_0 q_0 = L^0 q_0$, $\|q_0\| = 1$. By Lemma A we get

$$P_\varepsilon q_0 \rightarrow P_0 q_0 \neq 0 \quad \text{as } \varepsilon \rightarrow 0,$$

and from this a contradiction if we assume the existence of a sequence $\varepsilon_n \rightarrow 0$ with the property that from $\lambda_n \in \sigma(L^{\varepsilon_n})$ it follows $\lambda_n \notin D$. Indeed in this case $P_{\varepsilon_n} \equiv 0$ for any $n \in \mathbb{N}$.

4. The autonomous case

Following the lines of the previous section we first define for $\varepsilon > 0$ and $T > 0$ the Poincaré map $V_T^\varepsilon : Y_\varepsilon^1 \rightarrow Y_\varepsilon^1$ associated to (6)-(7) as follows

$$V_T^\varepsilon(p) = U_\varepsilon(T, T_0)p + \int_0^{T_0} U_\varepsilon(T, T_0 - s) f_\varepsilon(T, w)(s) ds,$$

where $w(t) \in Y_\epsilon^1$, $t \in [0, T_0]$, is a solution of (6)-(7) with $w(0) = p$ and the operators are those defined in Section 2.

We then consider the linearization $L_T^\epsilon : Y_\epsilon^1 \rightarrow Y_\epsilon^1$ of V_T^ϵ around $\hat{w}^\epsilon(t) = w^\epsilon((T_\epsilon/T_0)t)$, where w^ϵ is a T_ϵ -periodic solution of (6)-(7), whose existence for sufficiently small $\epsilon > 0$ is guaranteed by Theorem B, namely

$$L_T^\epsilon q = U_\epsilon(T, T_0)q + \int_0^{T_0} U_\epsilon(T, T_0 - s) f'_\epsilon(T, \hat{w}^\epsilon(s)) \psi(s) ds,$$

where $\psi(t) \in Y_\epsilon^1$, $t \in [0, T_0]$, is the solution of the linearization of (6) around \hat{w}^ϵ , such that $\psi(0) = q$.

For $\epsilon = 0$ we also define $V_T^0 : H^1(\Omega) \times L^2(\Omega) \rightarrow H^1(\Omega) \times L^2(\Omega)$ and the corresponding linearization L_T^0 around w^0 . Consider the linear operator L_T^ϵ for T close to T_0 . One can show that it has the condensivity properties of the operator L^ϵ of Section 3. Also its spectrum has the properties indicated for the spectrum of L^ϵ .

In the sequel we assume the conditions of Theorem B. Therefore, in particular, we assume the eigenvalue $1 \in \sigma(L_{T_0}^0)$ is simple. In order to investigate orbital (in)stability of w^ϵ we need the following

Lemma 2. *If $\epsilon > 0$ is sufficiently small the eigenvalue $1 \in \sigma(L_{T_\epsilon}^\epsilon)$ is simple.*

Proof. We argue by contradiction, thus we assume that there exist sequences $\epsilon_n \rightarrow 0$ and $q_n, q'_n \in Y_{\epsilon_n}^1$ such that q_n, q'_n are linearly independent eigenvectors of $L_{T_{\epsilon_n}}^{\epsilon_n}$ with $\|q_n\|_{Y_{\epsilon_n}^1} = \|q'_n\|_{Y_{\epsilon_n}^1} = 1$ corresponding to $1 \in \sigma(L_{T_{\epsilon_n}}^{\epsilon_n})$.

For any $n \in \mathbb{N}$ we define a projection in $Y_{\epsilon_n}^1$ as

$$P_n q = q - \langle q, q_n \rangle_n q_n,$$

where $\langle \cdot, \cdot \rangle_n$ denotes the scalar product in $Y_{\epsilon_n}^1 = X_{\epsilon_n}^1 \times L^2(Q)$ which generates the norm as it is defined in Section 2. Consider now

$$P_n q'_n = q'_n - \alpha_n q_n,$$

where $\alpha_n = \langle q'_n, q_n \rangle$. That is

$$q'_n = \alpha_n q_n + P_n q'_n.$$

From this we obtain

$$L_{T_{\epsilon_n}}^{\epsilon_n} q'_n = \alpha_n L_{T_{\epsilon_n}}^{\epsilon_n} q_n + P_n q'_n$$

or equivalently

$$P_n q'_n = L_{T_{\epsilon_n}}^{\epsilon_n} P_n q'_n.$$

Clearly $P_n q'_n \neq 0$, otherwise q_n, q'_n are linearly dependent. Therefore the previous equation can be rewritten as

$$\frac{P_n q'_n}{\|P_n q'_n\|_{Y_{\varepsilon_n}^1}} = L_{T_{\varepsilon_n}}^{\varepsilon_n} \frac{P_n q'_n}{\|P_n q'_n\|_{Y_{\varepsilon_n}^1}}.$$

Observe that $P_n q'_n$ is orthogonal to q_n . Now, passing to the limit as $n \rightarrow \infty$, by Lemma A (which still holds in the autonomous case) and Theorem B we obtain

$$\widehat{q}_0 = L_{T_0}^0 \widehat{q}_0, \quad \|\widehat{q}_0\|_{H^1(\Omega) \times L^2(\Omega)} = 1.$$

Furthermore,

$$\widehat{q}_0 = \frac{P_0 q_0}{\|P_0 q_0\|_{H^1(\Omega) \times L^2(\Omega)}},$$

where $q_0 \in H^1(\Omega) \times L^2(\Omega)$ is the normalized eigenvector of $L_{T_0}^0$ corresponding to the eigenvalue 1 and

$$P_0 q = q - \langle q, q_0 \rangle_0 q_0$$

is the projection in $H^1(\Omega) \times L^2(\Omega)$ defined by the usual norm $(\langle \cdot, \cdot \rangle_0)^{1/2}$ in this space which is the limit of the considered norm in $Y_{\varepsilon_n}^1$ as $n \rightarrow \infty$.

Since \widehat{q}_0 is orthogonal to q_0 we have a contradiction. Moreover by a similar procedure we can show that there is no adjoint vectors to q_n and so $1 \in \sigma(L_{T_{\varepsilon_n}}^{\varepsilon_n})$ is simple. This completes the proof.

To conclude it is sufficient to observe that we can repeat the same arguments employed in the non-autonomous case to establish the analogous of Theorems 1 and 2 for the orbital stability and instability respectively.

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