

Exam of Discrete Event Systems - 18.02.2015

Exercise 1

A small manufacturing workstation consists of a machine M preceded by a one-place buffer B . The machine processes raw parts of two types, namely type 1 and type 2. Parts arriving when the system is full are rerouted to another workstation. For technological reasons, arrivals of type 1 parts are disabled after two consecutive arrivals of type 1 parts accepted in the system, and enabled again after the next arrival of a type 2 part accepted in the system. Arrivals of type 2 parts are always possible.

1. Define a logical model $(\mathcal{E}, \mathcal{X}, \Gamma, f, x_0)$ of the system, leaving the initial state x_0 undefined.
2. Assume that the system is initially empty and two consecutive arrivals of type 1 parts can be accepted; arrivals of type 1 parts have total lifetimes equal to 5.0, 3.0 and 8.0 min; arrivals of type 2 parts occur at times 12.0, 18.0 and 27.0 min; processing of type 1 parts requires 9.0, 7.0 and 8.5 min, and processing of type 2 parts requires 4.0, 3.5 and 5.0 min. Construct a timing diagram for the system sample path over the interval $[0.0, 25.0]$ minutes, and compute the fraction of time that arrivals of type 1 parts are disabled.
3. Assume that total lifetimes of the arrivals of type 1 parts follow a uniform distribution over the interval $[5.0, 8.0]$ min, whereas arrivals of type 2 parts occur every 4.0 min. Moreover, assume that at time $t = 0$ (initialization) the system is empty and arrivals of type 1 parts are disabled. Compute the probability that exactly one arrival of a type 1 part occurs over the interval $[0.0, 15.0]$ minutes.

Exercise 2

Consider the manufacturing workstation whose logical model was defined in item 1 of Exercise 1, and assume that the total lifetimes of the arrivals of type 1 parts follow an exponential distribution with rate $\lambda_1 = 0.2$ arrivals/minute; arrivals of type 2 parts are generated by a Poisson process with rate $\lambda_2 = 0.25$ arrivals/minute; processing times of type 1 and type 2 parts are exponentially distributed with expected values 8.0 and 6.0 minutes, respectively.

1. Assume that the system is full with two type 1 parts. Compute the probability that the system reaches with the minimum number of events a state where it is empty and arrivals of type 1 parts are enabled.

Exercise 3

Consider the manufacturing workstation whose logical model was defined in item 1 of Exercise 1 and whose stochastic clock structure is defined in Exercise 2.

2. Verify the condition $\lambda_{eff} = \mu_{eff}$ for the system at steady-state.
3. Compute the average waiting time in B of a generic part at steady state.
4. It is known that at time $t = 20$ minutes the arrival of a type 1 part occurs. Is it possible to apply the PASTA property to compute the probability that the arriving type 1 part is rejected? Why?

Exercise 4

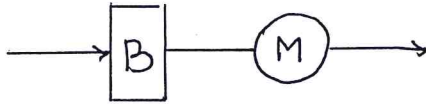
Consider a sequence of $N = 3$ genes. Each gene can be one of two types: A or a . From one generation to another, each gene can independently mutate to the other type. Let $p = 1/8$ be the probability that gene a mutates to gene A , and $q = 1/5$ the probability that gene A mutates to gene a .

1. Determine the average number of genes of type A in a gene sequence at steady state.
2. Assuming that the initial gene sequence is AAa , show the procedure to compute the probability that the gene sequence aaA is obtained before AAA and aaa .
3. Assuming that the initial gene sequence is AAa , show the procedure to compute the average number of generations to obtain the gene sequence aaA .

EXERCISE 1

1

1. The system can be represented as

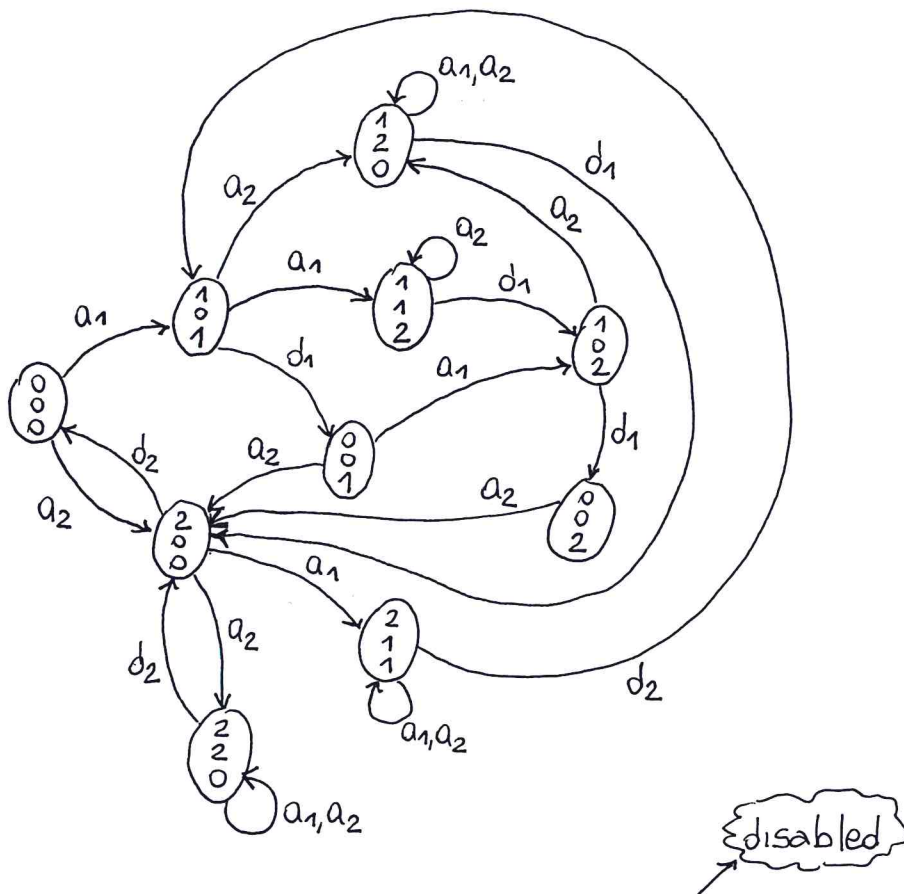


events $\mathcal{E} = \{a_1, a_2, d_1, d_2\}$

a_1 : arrival type 1
 a_2 : arrival type 2
 d_1 : termination type 1
 d_2 : termination type 2

state $\mathcal{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

$x_1 \rightarrow M: 0(\text{idle}), 1(\text{type 1}), 2(\text{type 2})$
 $x_2 \rightarrow B: 0(\text{empty}), 1(\text{type 1}), 2(\text{type 2})$
 $x_3 \rightarrow \# \text{ consecutive accepted type 1 arrivals} \in \{0, 1, 2\}$



REMARK: Notice that event a_1 is not possible in states $\begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$, $\begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$ and $\begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$ because two type 1 arrivals were consecutively accepted.

$$2. \quad \pi_0 = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

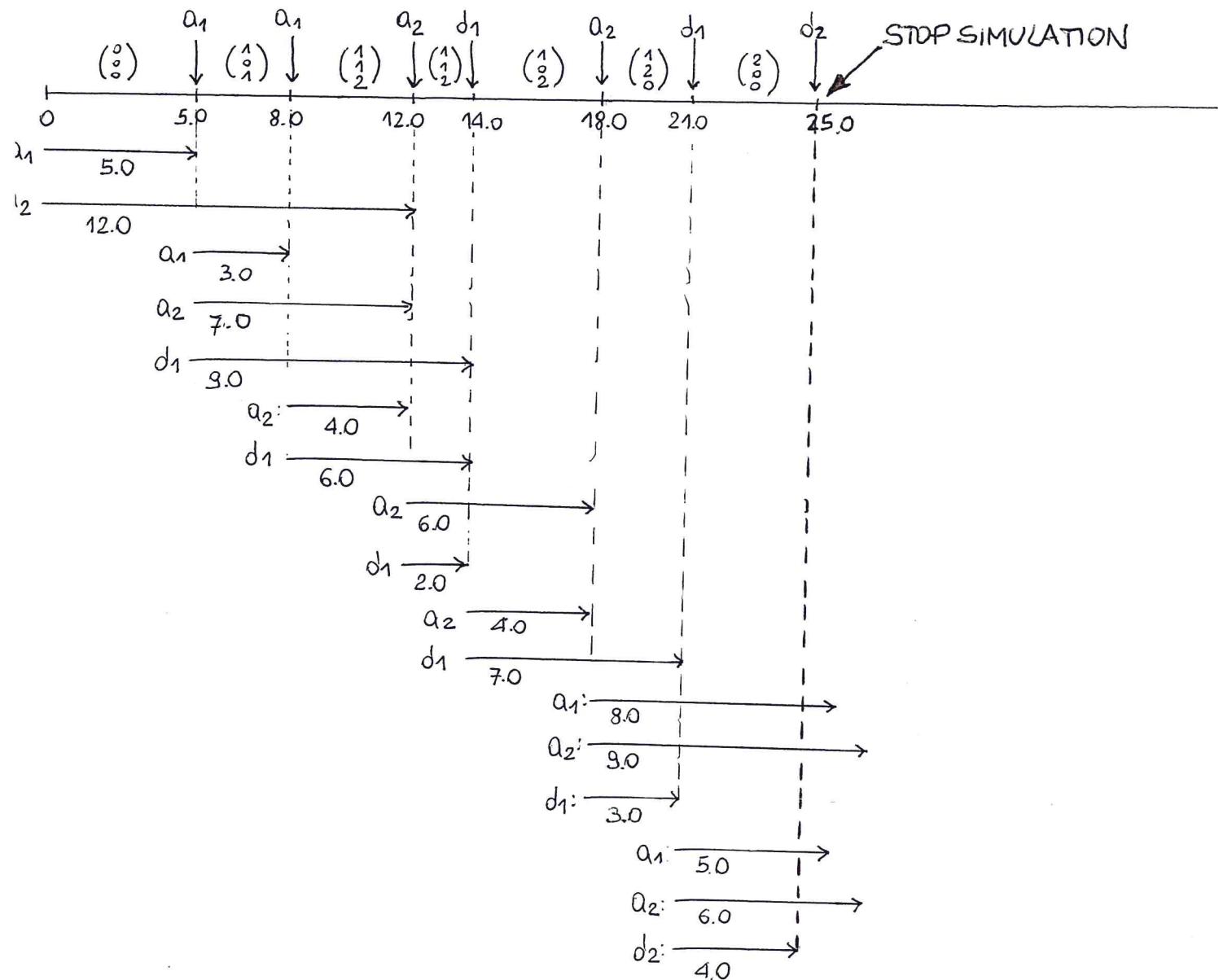
2

$$V_{a1} = \{5.0, 3.0, 8.0\}$$

$$Q_2 \text{ occurs at times } 12.0, 18.0 \text{ and } 27.0 \Rightarrow V_{a2} = \{12.0, 6.0, 9.0\}$$

$$V_{d1} = \{9.0, 7.0, 8.5\}$$

$$V_{d2} = \{4.0, 3.5, 5.0\}$$



The interval is $T = 25.0$ min.

Arrivals of type 1 are disabled from time 8.0 to time 18.0 $\Rightarrow T_{\text{disabled}} = 10.0$ min

$$\Rightarrow f_{\text{disabled}} = \frac{T_{\text{disabled}}}{T} = \frac{10}{25} = 0.4 = 40\%$$

3. $V_{a_1} \sim U(5.0, 8.0)$

3

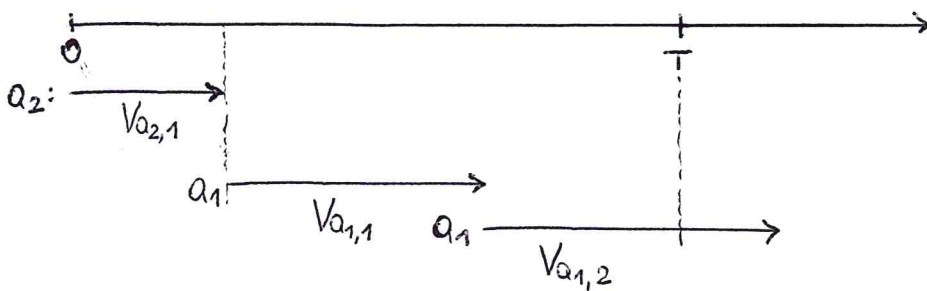
↓ generic lifetime of type 1 arrivals

$V_{a_2} = 4.0$ (deterministic)

↓ generic lifetime of type 2 arrivals

$x_0 = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$

First, we need event a_2 to enable event a_1 . Then, we require that the first occurrence of event a_1 is before $T = 15.0$, and the second after T .

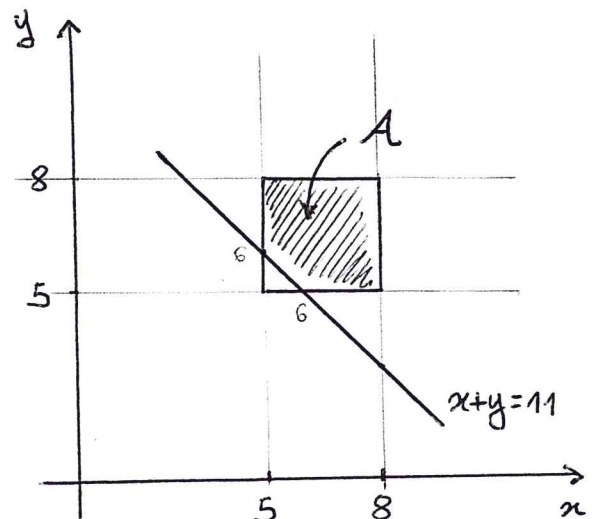


$\Rightarrow P(V_{a_{2,1}} + V_{a_{1,1}} \leq \overset{15.0}{T}, V_{a_{2,1}} + V_{a_{1,1}} + V_{a_{1,2}} > \overset{15.0}{T})$

$= P(\underbrace{V_{a_{1,1}} \leq 11}_{\text{always true because } V_{a_1} \sim U(5,8)}, V_{a_{1,1}} + V_{a_{1,2}} > 11) = P(\underbrace{V_{a_{1,1}}}_x + \underbrace{V_{a_{1,2}}}_y > 11)$

$= \frac{\text{area}(A)}{\text{area}(Q)} = \frac{3^2 - \frac{1^2}{2}}{3^2} = \frac{17}{18} \approx 0.9444$

square



EXERCISE 2

4

1. stochastic timed automaton $(\Sigma, \mathcal{X}, \Pi, f, x_0, F)$

the logical part
is the same as in
Exercise 1

$$F = \{F_{a_1}, F_{a_2}, F_{d_1}, F_{d_2}\}$$

$$F_{a_1}(t) = 1 - e^{-\lambda_1 t}, \quad t \geq 0 \quad \text{with } \lambda_1 = 0.2 \text{ arrivals/min}$$

$$F_{a_2}(t) = 1 - e^{-\lambda_2 t}, \quad t \geq 0 \quad \text{with } \lambda_2 = 0.25 \text{ arrivals/min}$$

$$F_{d_1}(t) = 1 - e^{-\mu_1 t}, \quad t \geq 0 \quad \text{with } \frac{1}{\mu_1} = 8.0 \text{ min} \Rightarrow \mu_1 = 0.125 \text{ services/min}$$

$$F_{d_2}(t) = 1 - e^{-\mu_2 t}, \quad t \geq 0 \quad \text{with } \frac{1}{\mu_2} = 6.0 \text{ min} \Rightarrow \mu_2 \approx 0.1667 \text{ services/min}$$

The current state is $X_k = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$. We have to reach state $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ with the minimum number of events. It is not possible with one, two or three events. It can be done with four events. There are two favorable cases:

$$\bullet \quad \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} \xrightarrow{d_1} \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \xrightarrow{d_1} \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} \xrightarrow{a_2} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \xrightarrow{d_2} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{with probability } \frac{\mu_1}{\lambda_2 + \mu_1} \cdot \frac{\mu_1}{\lambda_2 + \mu_1} \cdot 1 \cdot \frac{\mu_2}{\lambda_1 + \lambda_2 + \mu_2}$$

$$\bullet \quad \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} \xrightarrow{d_1} \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \xrightarrow{a_2} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \xrightarrow{d_1} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \xrightarrow{d_2} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{with probability } \frac{\mu_1}{\lambda_2 + \mu_1} \cdot \frac{\lambda_2}{\lambda_2 + \mu_1} \cdot \frac{\mu_1}{\lambda_1 + \lambda_2 + \mu_1} \cdot \frac{\mu_2}{\lambda_1 + \lambda_2 + \mu_2}$$

$$\Rightarrow P(\dots) = \left(\frac{\mu_1}{\lambda_2 + \mu_1} \right)^2 \frac{\mu_2}{\lambda_1 + \lambda_2 + \mu_2} + \frac{\mu_1}{\lambda_2 + \mu_1} \frac{\lambda_2}{\lambda_2 + \mu_1} \frac{\mu_1}{\lambda_1 + \lambda_2 + \mu_1} \frac{\mu_2}{\lambda_1 + \lambda_2 + \mu_2} \approx 0.0431$$